

note: $A = l(d-x)$

$$P = Vi$$

$$P_{\text{loss}} = Ri^2$$

$$dW_e = P dt = Vidt$$

$$dW_{\text{loss}} = P_{\text{loss}} dt = Ri^2 dt$$

$$dW_m = f dx$$

$$dW_{\phi} = dW_e - dW_{\text{loss}} - dW_m$$

$$e = \frac{dd}{dt} \Rightarrow edt = dd$$

$$dW_{\phi} = Vidt - Ri^2 dt - f dx$$

$$= i(V - Ri) dt - f dx$$

$$= i edt - f dx$$

$$dW_{\phi} = i dd - f dx$$

$$W_{\phi}(d, x), i(d, x), f(d, x)$$

$$dW_{\phi} = \frac{\partial W_{\phi}(d, x)}{\partial d} dd + \frac{\partial W_{\phi}(d, x)}{\partial x} dx$$

$$W_{\phi} = \frac{1}{2} L_{11} i_1^2 + L_{12} i_1 i_2 + \frac{1}{2} L_{22} i_2^2$$

Lorentz's Law

$$\vec{f} = i \vec{l} \times \vec{B}$$

$$f = - \frac{\partial \omega_{\phi}(d, x)}{\partial x}$$

$$i = \frac{\partial \omega_{\phi}(d, x)}{\partial d}$$

$$\omega_{\phi}(d, x) = \int_0^d i \, dd$$

$$L = \frac{d}{i} \Rightarrow d = Li$$

$$\omega_{\phi}(d, x) = \int_0^i Li \, di$$

$$= \frac{1}{2} Li^2 = \frac{1}{2} \frac{d^2}{L}$$

$$L = \frac{d}{i} = \frac{N\phi}{i} = \frac{N\phi}{\frac{N i}{R}} = N \frac{N i}{R}$$

$$L = \frac{N^2}{R} = \frac{N^2}{\frac{2g}{\mu_0(d-x)}} = \frac{N^2 \mu_0 l (d-x)}{2g}$$

$$\omega_{\phi}(d, x) = \frac{1}{2} \frac{d^2}{L}$$

$$= \frac{1}{2} \frac{d^2}{\frac{N^2 \mu_0 l (d-x)}{2g}}$$

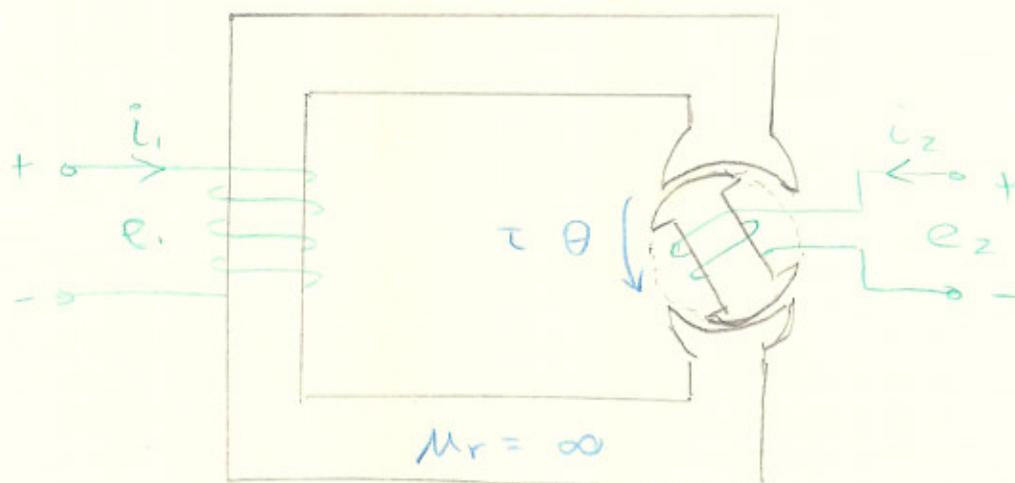
$$= \frac{g d^2}{N^2 \mu_0 l (d-x)}$$

$$f = - \frac{\partial W_{\phi}(d, x)}{\partial x}$$

$$= - \frac{g d^2}{N^2 \mu_0 l} \frac{(-1)(-1)}{(d-x)^2}$$

$$d = N\phi = N \frac{Q}{R} = \frac{N^2 i}{R} = \frac{N^2 i}{\frac{2g}{\mu_0 l (d-x)}} = \frac{N^2 \mu_0 l (d-x) i}{2g}$$

$$f = - \frac{\mu_0 l (N i)^2}{4g}$$



$$\begin{aligned} dW_e &= P_1 dt + P_2 dt \\ &= i_1 e_1 dt + i_2 e_2 dt \\ &= i_1 dd_1 + i_2 dd_2 \end{aligned}$$

$$dW_m = \tau d\theta$$

$$\begin{aligned} dW_{\phi} &= dW_e - dW_m \\ &= i_1 dd_1 + i_2 dd_2 - \tau d\theta \end{aligned}$$

$$W_{\phi} = (d_1, d_2, \theta)$$

$$dW_{\phi} = \frac{\partial W_{\phi}}{\partial d_1} dd_1 + \frac{\partial W_{\phi}}{\partial d_2} dd_2 + \frac{\partial W_{\phi}}{\partial \theta} d\theta$$

$$\therefore \dot{i}_1 = \frac{\partial W_{\phi}}{\partial d_1} \quad \dot{i}_2 = \frac{\partial W_{\phi}}{\partial d_2} \quad \tau = -\frac{\partial W_{\phi}}{\partial \theta}$$

given that...

$$L_{11} = 0.001(3 + \cos 2\theta)$$

$$L_{12} = L_{21} = 0.3 \cos \theta$$

$$L_{22} = 30 + 10 \cos 2\theta$$

Find τ for $\dot{i}_1 = 0.8 \text{ A}$ & $\dot{i}_2 = 0.01 \text{ A}$

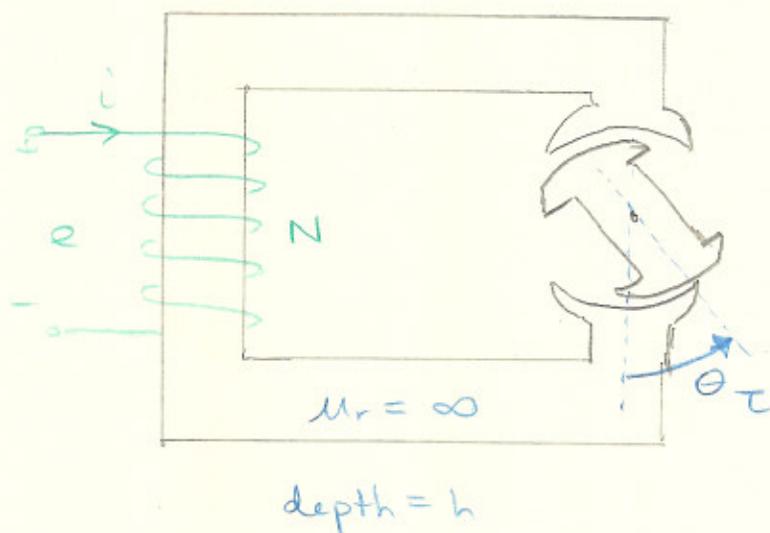
note: $\tau = \frac{\partial W_{\phi}(\dot{i}_1, \dot{i}_2, \theta)}{\partial \theta}$

$$f = \frac{\partial W_{\phi}(\dot{i}_1, \dot{i}_2, x)}{\partial x}$$

$$W_{\phi} = \frac{1}{2} L_{11} \dot{i}_1^2 + L_{12} \dot{i}_1 \dot{i}_2 + \frac{1}{2} L_{22} \dot{i}_2^2$$

$$\frac{dW_{\phi}}{d\theta} = \tau = \frac{1}{2} \dot{i}_1^2 \frac{dL_{11}}{d\theta} + \dot{i}_1 \dot{i}_2 \frac{dL_{12}}{d\theta} + \frac{1}{2} \dot{i}_2^2 \frac{dL_{22}}{d\theta}$$

$$\begin{aligned} \tau &= \frac{1}{2} \times 0.8^2 \times 0.001 (-2 \sin 2\theta) + 0.8 \cdot 0.01 \times 0.3 \\ &\quad (-\sin \theta) + \frac{1}{2} \times 0.01^2 \times 10 (-2 \sin 2\theta) \\ &= -0.00164 \sin 2\theta - 0.0024 \sin \theta \end{aligned}$$



$$W_{\phi}(d, \theta) = \frac{1}{2} \frac{d^2}{L}$$

$$W_{\phi}(i, \theta) = \frac{1}{2} L i^2$$

$$\tau = \frac{\partial W_{\phi}(i, \theta)}{\partial \theta}$$

$$\tau = \frac{1}{2} i^2 \frac{\partial L}{\partial \theta}$$